

Machine Intelligence and Robotic Control

Review:

- Algorithmic and Soft Computing Approaches to Robot Motion Planning** *1*
Dilip Kumar Pratihar

Papers:

- Multi-Branch Structure of Layered Neural Networks** *17*
Takashi Yamashita, Kotaro Hirasawa, and Jinglu Hu
- Evolutional Acquisition of Communication Between Agents Using Genetic Network Programming** *25*
Shinji Eto, Toru Eguchi, Kotaro Hirasawa, and Jinglu Hu